

# Delay Compensation For Nonlinear, Adaptive, And PDE Systems

by Miroslav Krstic

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Compensation for Nonlinear, Adaptive, and PDE Systems . Miroslav is a coauthor of the books Nonlinear and Adaptive Control Design (New . Delay Compensation for Nonlinear, Adaptive, and PDE Systems (Boston: Adaptive trajectory tracking despite unknown input delay and . - Hal nonlinear systems with delays and of nonlinear PDE systems. We design compensation of delays (i.e., after the control signal reaches the system for the first time, the system . 3.2 Adaptive Control for Systems with Uncertain Plant Pa-. Adaptive Fault-Tolerant Control for Time-Delay Nonlinear Systems . 9th IFAC Workshop on Time Delay Systems . in his new book „Delay Compensation for Nonlinear, Adaptive and PDE Systems“ (Birkhauser, Oct. 2009). From Classical Delay Compensation to Delay-Adaptive Predictor . Boundary control of PDEs: A course on backstepping designs. M Krstic, A Smyshlyaev Delay compensation for nonlinear, adaptive, and PDE systems. M Krstic. Professor Miroslav Krstic ACSE Visit - University of Sheffield ?001412127 001\_\_ 1412127 001412127 003\_\_ SzGeCERN 001412127 005\_\_ 20151106231354.0 001412127 020\_\_ \$\$